Hands are an integral part of the human body, and they are able to carry out a variety of tasks that are commonly performed by the hands. The palm consists of an outer carbon fiber body with the outer shell bifurcated in the dorsal and lateral planes, and an inner frame, which acts as a shimmy sphere and contains the thumb mechanism and all four fingers. These 250 cc-sized five-finger bending triggers are installed in a groove and have a total volume of 250 cc, with stroke triggering actuated by the palm of the hand rather than the electric hand.F. Lotti et al. were investigated by F. Lotti et al. A workable replica of the hand was developed, with a regular structure with four identical fingers mingled with each finger, and the thumb being affixed to the wrist frame. Further research is focused on reviving these functions, which aim to create specialized devices that assist amputees in reducing their effort and time. Stanford University was responsible for the development of the tendon drive [3] and Iowa State University, USA [4] for the connecting rod motor, while the first came from the Virginia Tech Institute [4]. The driving mechanisms driving the prosthetic hand are based on two fundamental types, tendon drive and connecting rod drive [2], which are frequently used in this area. The absence of a functional limb, or limb that is permanently disabled, means the loss of the hand. The prosthesis' low cost, high performance, simple design [5], aesthetics, and low weight [6] provide users with a reliable prosthesis that is still highly dependable and can be developed in the future M. C. Carrozza et al. Cyber-Hand was invented to provide 16 degrees of freedom and 6 operations for each finger, allowing each Finger-Friendly to move up and down in two degrees. A compatible layer, which mimics the human soft tissue function, covers the internal structure and imbues it with the same level of soft tissue. The size of the device is similar, and control is restricted to a small set of handles that can be used for different tasks. The Cyber-Hand can be re-created as many different versions, compared to human hands. The modeled hand has .a resemblance in size to the real hands of humans